Climate variation and population dynamics

1	
2	Altered precipitation dynamics lead to a shift in herbivore dynamical regime
3	Adam Pepi <sup>1,2</sup> *, Marcel Holyoak <sup>3</sup> , Richard Karban <sup>2</sup>
4	<sup>1</sup> Graduate Group in Ecology, University of California Davis, Davis CA 95616
5	<sup>2</sup> Department of Entomology and Nematology, University of California Davis, Davis CA 95616
6	<sup>3</sup> Department of Environmental Science and Policy, University of California Davis, Davis CA 95616
7	*Corresponding author. Email: <u>adampepi@gmail.com</u>
8	Keywords: climate change, population dynamics, stochastic resonance, delayed density-
9	dependence
10	Type of article: Letter
11	Abstract word count: 147
12	Main text word count: 3882
13	Number of references: 43
14	Number of figures: 4
15	Number of text boxes: 0
16	Number of tables: 1
17	Statement of authorship: AP, RK, and MH conceived the study, AP conducted the analyses and
18	wrote the manuscript, RK collected the census data, and RK and MH provided editorial advice.
19	Data accessibility statement: The supporting data will be archived in HAL upon publication.
20	
21	
22	
23	
24	
25	

#### 26 Abstract

27 The interaction between endogenous dynamics and exogenous environmental variation is 28 central to population dynamics. Although investigations into the effects of changing mean climate is 29 widespread, changing patterns of variation in environmental forcing also affect dynamics in complex ways. Using wavelet and time-series analyses, we identify a regime shift in the dynamics of a moth 30 31 species in California from shorter to longer period oscillations over a 34-year census, and 32 contemporaneous changes in regional precipitation dynamics. Simulations support the hypothesis that 33 shifting precipitation dynamics drove changes in moth dynamics, possibly due to stochastic resonance 34 with delayed density-dependence. The observed shift in climate dynamics and the interaction with 35 endogenous dynamics mean that predicting future population dynamics will require information on 36 both climatic shifts and their interaction with endogenous density dependence, a combination that is 37 rarely available. Consequently, models based on historical data may be unable to predict future 38 population dynamics.

#### 39 Introduction

40 The dynamics of populations reflect the interplay between endogenous demographic and 41 exogenous environmental drivers. Since its inception, population ecology has focused on debates about 42 the relative contribution of these components to the generation of several salient phenomena observed 43 in the dynamics of natural and laboratory populations, particularly cyclic fluctuations (Nicholson 1933; 44 Andrewartha & Birch 1954; Barraquand et al. 2017). More recently, it has been recognized that both 45 endogenous and exogenous drivers play important roles in generating observed population dynamics, 46 and that endogenous deterministic dynamics and exogenous environmental noise or perturbations may 47 combine to generate differing dynamics than would be expected for either component alone (Bjørnstad & Grenfell 2001; Turchin 2003; Barraquand et al. 2017). There has been additional motivation to 48 49 understand the effects of climate on population dynamics as the effects of global climate change on the 50 planet's biota have become more apparent (Walther et al. 2002; Parmesan 2006). Climate change is

51 expected to result in increased climate variability (Coumou & Rahmstorf 2012), as well as alterations 52 to patterns of large-scale climate oscillations (Simon Wang *et al.* 2017), both of which are important 53 drivers of local population dynamics. In a prominent example, changes in oceanic temperature 54 oscillation regimes have resulted in dramatic changes to precipitation patterns in California (Simon 55 Wang *et al.* 2017), with large impacts to society and natural ecosystems.

Climate variation can have direct effects on interannual fluctuations in population size or may 56 57 interact in complex ways with endogenous dynamics of populations. For example, environmental 58 perturbations can sustain population oscillations that might otherwise decay to a stable equilibrium (Tomé & De Oliveira 2009; Barraquand et al. 2017). Climate change has also appeared to cause the 59 collapse of population cycles of many species across Europe (Ims et al. 2008; Cornulier et al. 2013). 60 Environmental perturbations with different spectra of variability can also amplify, dampen, or impose 61 62 their own spectra on oscillatory populations depending on the "colour" (temporal autocorrelation) of 63 environmental spectra relative to the spectra of the endogenous dynamics of the population (Greenman 64 & Benton 2003). Changing climate can also interact in a non-stationary way with population 65 dynamics, such as transient effects of long-term climate oscillations on epidemic disease cycles (Rodó 66 et al. 2002; Cazelles et al. 2005). However, testing for such effects on population dynamics of other 67 kinds of organisms requires rarely available long-term population data.

68 In the present study, we examined how changing precipitation dynamics interact with the 69 endogenous population dynamics of an extensively studied insect species, the Ranchman's tiger moth 70 (Arctia virginalis). We analyzed 34 years of census data from northern California, over a period during 71 which there have been significant shifts in the dynamics of regional climate (Simon Wang et al. 2017). Using time series analyses and simulations, we tested for changes in population dynamics, and 72 compared multiple possible mechanisms for observed shifts. Using simulations, we tested the 73 74 hypotheses that shifting dynamics were because 1. underlying dynamics were first masked and later 75 amplified by precipitation, 2. underlying dynamics were first amplified and later masked by

precipitation, or 3. dynamical shifts were driven completely exogenously by changing precipitation
dynamics.

78 Materials & Methods

## 79 *Description of system*

Ranchman's tiger moth (Arctia virginalis) is a univoltine, day-active Arctiine moth, native to 80 much of the western United States. Adult moths emerge in late spring or early summer and have a 81 82 flight period of several weeks during which they do not feed. Eggs are laid on low vegetation or litter 83 in early summer; small caterpillars hatch soon after eggs are laid. Early instar caterpillars are heavily preved upon by ground nesting ants, and are potentially food-limited during seasonal senescence of 84 vegetation in Mediterranean summers (Karban et al. 2013, 2017). Time series analyses have shown 85 that greater precipitation during the previous year results in greater population growth, possibly due to 86 87 increased food availability during the summer drought (Karban & de Valpine 2010; Karban et al. 88 2017). Caterpillars feed continuously over the winter period and do not diapause in California. After 89 this, they move up to feed on higher vegetation and become more visible in late winter in California. 90 Caterpillars are generalists, with a preference for alkaloid-containing hosts (English-Loeb et al. 1993; 91 Karban et al. 2010). Caterpillars are also frequently attacked by tachinid parasitoids, *Thelaira* 92 americana (Karban & de Valpine 2010), which are specialists on Arctiine moths (Arnaud 1978), and 93 may functionally be specialists on Ranchman's tiger moth at our study site, the Bodega Marine 94 Reserve. However, analyses have suggested that parasitism has little effect on caterpillar population 95 dynamics (Karban & de Valpine 2010). Caterpillar populations at the Bodega Marine Reserve and 96 other sites often exhibit high mortality rates after high population density years due to a granulovirus. Monitoring at Bodega and other sites has shown delayed density-dependent infection and mortality 97 98 rates due to granulovirus (Pepi, Pan & Karban, unpublished data).

99 Censuses

100	Caterpillar censuses were conducted on perennial evergreen yellow bush lupine (Lupinus
101	arboreus) bushes at Bodega Marine Reserve in Sonoma County, California (38°19'05"N,
102	123°04'12"W). The number of caterpillars on 10 lupine bushes in the same patch were counted yearly
103	from 1986 to 2019 (>10 in 1986). Bushes were censused in the last week of March each year. Previous
104	repeated censuses within a year between late February and the end of March suggest that population
105	estimates were unlikely to vary significantly due to changes in seasonal phenology from year to year
106	(Karban and Grof-Tisza, unpublished data), because of the long development period of caterpillars and
107	their limited mobility during this stage. The same lupine bushes were censused each year; however, the
108	identity of bushes changed because these lupines were short lived (< 7yr). To account for variation in
109	sampling effort, area of each lupine bush censused was measured to calculate caterpillar density per m <sup>2</sup>
110	(plotted as caterpillars per 100 m <sup>2</sup> in Figure 3 for legibility). Precipitation was recorded at the site as
111	part of ongoing climate monitoring by the University of California and using a rain gauge at the study
112	site (US Weather Bureau type manual rain gauge prior to 1992 and an optical rain gauge ORG-815,
113	Optical Scientific, Gaithersburg, MD since 1992 with a Hydrological Services TB4 tipping bucket,
114	Campbell Scientific, Ogden, UT since 2003). For analyses, total annual precipitation within the
115	hydrologic year was calculated (from October 1st of the previous year to September 30th of the current
116	year).

117 *Statistical analyses* 

To test for non-stationary relationships between precipitation and caterpillar dynamics over time, wavelet analysis was conducted separately on logged and scaled caterpillar and scaled precipitation time series, and as wavelet coherence analyses on both series (Figure 3). Scaling was accomplished by subtracting the mean and dividing by the standard deviation (scale() in R). Analyses were conducted using the package BIWAVELET (Gouhier *et al.* 2019), using Morlet wavelet transforms. In addition, change-point analyses were conducted using the SEGLM and TSDYN packages (Antonio & Stigler 2009; Stigler 2019), with a model containing direct and delayed density-dependence, and a

separate model also including precipitation as a covariate. We included precipitation as a covariate
based on previous knowledge that precipitation was important to dynamics. We included direct densitydependence based on previous detection in time series analyses (Karban & de Valpine 2010), and
delayed density-dependence based on wavelet periodogram results and the observation of delayeddensity dependent mortality from granulovirus in field studies (Pepi, Pan & Karban, unpublished data).
Models with and without a threshold (*C*) were compared using AIC. Break point models were of the
form:

132 
$$X_t \sim Normal(a_{0,1} + a_{1,1}X_{t-1} + a_{2,1}X_{t-2} + \beta_{1,1}Precip_{t-1}, \sigma_1^2) \mid t \le C$$

133 
$$X_t \sim Normal(a_{0,2} + a_{1,2}X_{t-1} + a_{2,2}X_{t-2} + \beta_{1,2}Precip_{t-1}, \sigma_2^2) \mid t \ge C,$$

134 in which  $X_t$  is log population density [ln(count/area)],  $a_0$  is the intercept,  $a_1$  is direct density 135 dependence,  $a_2$  is delayed density dependence, and  $\beta_1$  is the effect of precipitation,  $\sigma^2$  is the variance, 136 with a separate parameter estimate for each before and after the threshold.

Bayesian state space population models using a Poisson observation process were constructed 137 138 to test for direct and delayed density-dependence and effects of precipitation. We conducted this as a 139 separate step from testing for thresholds to avoid identifiability issues due to limited data availability. 140 We primarily examined a model with the same process structure as breakpoint models, including direct 141 and delayed density dependence and an effect of precipitation, based on a priori knowledge about the 142 system. For comparison, models with all possible combinations of variables were generated and 143 compared using WAIC (Vehtari et al. 2017). State space models were fit to the time series from 1986-144 2004 and 2004-2019 separately and results compared, based on findings of change-point analyses. The 145 full state-space model was of the form:

146  $Y_t \sim Poisson(\exp(X_t) * area_t)$ 

147 
$$X_t \sim Normal(a_0 + a_1 X_{t-1} + a_2 X_{t-2} + \beta_1 Precip_{t-1}, \sigma^2),$$

148	in which $Y_t$ is caterpillar count, $X_t$ is the estimated population density state on a log scale, $area_t$ is the
149	area of lupine sampled, $a_0$ is the intercept, $a_1$ is direct density dependence, $a_2$ is delayed density
150	dependence, $\beta_1$ is the effect of precipitation, and $\sigma^2$ is the process variance. Models were fitted in JAGS
151	with interface in R using RJAGS (Plummer 2019) and R2JAGS (Yu-Sung Su & Yajima 2015). We used a
152	vague regularizing Gaussian prior for all parameters [Normal(0, 10)], except for the process variance
153	( $\sigma^2$ ), for which we used a uniform prior [ <i>Uniform</i> (0, 10)]. Model convergence was assessed using
154	the CODA (Martyn <i>et al.</i> 2019) package, by visualizing chains (Figures S1-3) and the $\hat{R}$ convergence
155	criterion (Gelman & Rubin 1992). We also conducted one-step ahead simulations as posterior
156	predictive checks (Figures S4-6), for which P-values were 0.5±0.03, indicating acceptable model fit.
157	Models were fitted using 3 MCMC chains of 20,000 iterations, with 1,000 iterations of burn-in. All $\hat{R}$
158	values were <1.001.

To ascertain the mechanisms driving shifts in dynamics, we conducted deterministic simulations 159 160 by projecting populations into the future using parameter values sampled from the posteriors of fitted 161 state space process models. Simulations were also conducted with fitted density-dependence 162 parameters, but with all precipitation effects drawn from the posterior of the model with the highest 163 estimated effect of precipitation (from the second half of the series;  $\beta_1 = 0.922$ ). Another simulation was 164 conducted using the fitted process model from the second part of the series, but with density-dependent parameters  $(a_1, a_2)$  set to zero. For simulations, observed starting population sizes were used, and 165 166 observed precipitation values were used for the entire period. For each mechanistic scenario, 10,000 167 simulations were conducted, each based on a separate draw from posteriors. Simulated population trajectories were wavelet transformed, and a dissimilarity relative to the true population series was 168 calculated based on the method of Rouyer et al. (2008b) (Table S3, Figures S7-8), all using BIWAVELET 169 170 (Gouhier et al. 2019).

171 Results

172 Caterpillar population dynamics exhibited a clear regime shift during our study. Wavelet 173 spectrograms show that dominant oscillatory periods of caterpillar and precipitation dynamics shifted 174 from short-period (2-3 yr) to long-period oscillations (4-6 yr; Figure 1c,e), though periodicity was only 175 significant at the 95% level for precipitation in the first part of the series (2-3 yr periodicity from 176 ~1992-1999) and caterpillars in the second part of the series (4-6 yr periodicity from ~2003-2013). 177 Precipitation dynamics changed after ca. 1999, and caterpillar dynamics changed shortly thereafter (ca. 178 2002). Wavelet coherence between precipitation and caterpillar numbers shifted from a 3-year period in 179 the early part of the series to a 3-6 year period after ca. 2005 (Figure 1g), suggesting a role of precipitation in shifts in caterpillar population dynamics. The observed shift in precipitation dynamics 180 181 in turn was likely caused by shifting oceanic climate oscillations; the Pacific Decadal Oscillation and 182 offshore sea surface temperature switched from a warm to a cold phase after 1999, which resulted in 183 shifts in dynamics of several marine species at that time (Cloern et al. 2010; Thomson et al. 2010). A 184 similar climate regime of high-amplitude, long-period oscillations between multi-year drought and high 185 precipitation is expected to be the norm for California in the future (Swain et al. 2018). 186 Change-point analyses found a change in dynamics with a threshold in 2002 (AAIC=4.8 relative 187 to model without a threshold) in a model without precipitation, or in 2004 in a model including 188 precipitation ( $\Delta AIC=6.5$ ). Before the threshold, direct density-dependence was estimated to be negative 189 and this became positive after the threshold, though there was limited evidence that these estimates 190 were different from zero (0.10>P>0.09; see Table 1). In models that included precipitation, its effects 191 were always near zero before the threshold, and strongly positive after the threshold (Table 1). Delayed 192 density-dependence had negative parameter estimates in all models, with the most evidence for delayed 193 density dependence after the threshold in the model without precipitation (P=0.019), and weaker 194 evidence otherwise (P>0.2).

Results from Bayesian Poisson state-space models corresponded broadly with those from the change point analyses, showing a shift in dynamics from the first to the second period. The full model

197 was an acceptable fit relative to other model structures tested, though large differences were not 198 detected due to the state-space structure and limited data availability (Table S1;  $\Delta$ WAIC<2 for all 199 models). 90% high density posterior intervals (HDPI) that are superior for characterizing MCMC 200 posteriors (because of more samples in the tails; Kruschke 2014) show the following: Considering the full model fitted to the entire series (1986-2019), direct density-dependence was weak ( $a_1 = -0.11$ ; 90% 201 HDPI: -0.23 - 0.47), delayed density-dependence was negative ( $a_2 = -0.3$ ; 90% HDPI: -0.63 - 0.03]), 202 203 and there was a weak positive effect of rainfall ( $\beta_1 = 0.30$ ; 90% HDPI: -0.08 – 0.70; Figure 2). For the 204 first part of the series (1986-2004), direct density-dependence was negative ( $a_1 = -0.63$ ; 90% HDPI: -1.19 – -0.10), delayed density-dependence was negative but weak ( $a_2 = -0.27$ ; 90% HDPI: -0.78 – 205 0.26), and the effect of precipitation was weak ( $\beta_1 = 0.26$ ; 90% HDPI: -0.17 – 0.68; Figure 2). For the 206 second part of the series (2004-2019), direct density-dependence was positive ( $a_1 = 0.46$ ; 90% HDPI: 207 0.03 – 0.82), delayed density-dependence was negative but weak ( $a_2 = -0.19$ ; 90% HDPI: -0.63 – 208 0.36), and the effect of precipitation was stronger and positive ( $\beta_1 = 0.92$ ; 90% HDPI: 0.2 - 1.75; 209 210 Figure 2). Overall, the results of these models provide evidence for a shift from negative to positive 211 direct density-dependence from the first to the second part of the series, with non-overlapping 90% intervals between the two parts ( $a_1 = -1.19 - -0.13$  vs. 0.03 - 0.82), although 95% intervals did have a 212 213 marginal overlap ( $a_1 = -1.29 - 0.03$  vs. -0.05 - 0.96; Figure 2). This corresponds with a shift from type 214 III to type IV dynamics (Figure 3) and a shift from shorter to longer period dynamics. 215 The results from simulation analyses suggested that the long-period dynamics observed in the 216 second part of the series (2004-2019) could best recreate the observed dynamics. Specifically, there 217 was some evidence that endogenous dynamics as parameterized from the second part of the series best 218 recovered the observed shift in dynamical regime when used to simulate dynamics for the entire series, 219 based on the maximum a posteriori dissimilarity calculated from wavelet transforms (Figure 4, 220 S1, Table S3; Rouver et al. 2008; Gouhier et al. 2019). This was the case both in simulations which

221 used the original fitted precipitation parameters, and in simulations in which the effect of precipitation 222 was set to the same value to examine solely the effect of different endogenous dynamics (lowest 223 dissimilarity: *d*=17.6; whole series: *d*=22.1, 18.5; first part: *d*=22.8, 21.4; Figure 4, S1, Table S3). 224 Simulations including density-dependence reproduced dynamics somewhat better (d=17.6) than 225 simulations without density-dependence (d=19.7). The broad posterior intervals of simulation results 226 indicated substantial uncertainty as to the mechanisms driving observed shifts (Figure 4). However, to 227 the extent that we are interested in the question of whether specific endogenous dynamics (i.e., specific 228 parameter values) underlie the observed shift in dynamics, the point estimates from the second part of the series best reproduced dynamics. Overall, results were consistent with the interpretation that the 229 230 shift in dynamics was driven either by an interaction between endogenous dynamics and precipitation, or possibly solely by precipitation (Figure 4). 231

## Discussion

233 Our analyses together suggest that over the census period, the changing structure of variation in 234 precipitation dynamics interacted with the structure of endogenous dynamics of caterpillar populations 235 to generate novel dynamics. This resulted in higher amplitude, long-period oscillations in the second 236 part of the series (2004-2019), in which both the lowest (2005) and the highest (2019) caterpillar 237 population densities were observed. This is in contrast with the first part of the census (1986-2004) 238 which was characterized by weak lower amplitude and short-period oscillations. These shifts in 239 oscillatory period corresponded with a shift from negative direct and delayed density-dependence (type 240 III dynamics) to positive direct and negative delayed density dependence (type IV dynamics). Although 241 many parameter posterior intervals overlapped zero, there was strong statistical evidence for our main hypothesis, showing a shift from direct density-dependence to negative density dependence during the 242 study (Figure 2,3). This shift in dynamics appears to have been due to changing patterns of variation in 243 244 environmental forcing and illustrates the complexity of forecasting impacts of changes in both mean 245 and pattern of variation in future climates on population dynamics.

246 Simulation studies have shown that environmental noise can resonate with the dominant period 247 of deterministic endogenous dynamics of a system if the noise spectra includes the period of the 248 deterministic system (Royama 1992; Alonso et al. 2007). Environmental variation may also impose its 249 own spectral signature on population dynamics with different dominant periods (Greenman & Benton 250 2003). Given these observations, there are multiple possible mechanistic explanations for the shift in dynamics observed in this study. One possible interpretation is that the interaction between the 251 252 endogenous dynamical structure of this population with changing exogenous perturbation (i.e., 253 precipitation) obscured the endogenous dynamics in one part of the series, but not the other (Ranta et 254 al. 2000). Another interpretation is that dynamical shifts may have been entirely externally forced by changing precipitation dynamics. We distinguished between these possibilities by simulating 255 256 deterministic population trajectories from fitted state-space models using observed precipitation, which 257 indicated that the dynamics from the second part of the series were somewhat more likely to have 258 represented the underlying endogenous dynamics of the system. This indicates that short-period 259 oscillations in precipitation may have interfered with delayed density-dependence in the endogenous 260 dynamics to generate the observed population dynamics in the first half of the caterpillar time series. By imposing short-period oscillations onto population dynamics, external forcing by precipitation may 261 262 have created only the appearance of negative direct density-dependence. During the second half of the 263 series, longer period oscillations of precipitation may have resonated with delayed density-dependence 264 and generated high-amplitude long-period oscillations. This interpretation is supported by the fact that 265 simulations including negative direct density-dependence (*i.e.*, the model from the first part of the 266 series) prevented the resonance of precipitation with delayed density-dependence and did not recreate the original dynamics quite as effectively as models with positive direct density-dependence (Figure 4, 267 S7-8, Table S3). Furthermore, the possibility that observed shifts in dynamics were driven completely 268 269 externally by precipitation seems less likely because simulations lacking density-dependence did not as 270 effectively recover the original shift in dynamics as simulations including density-dependence.

However, if we consider the uncertainty of parameter estimates in the simulation results, we cannot be confident in distinguishing between alternative scenarios, as all simulation posteriors overlap substantially (Figure 4). Nonetheless, despite the limited information contained within our 34-year population time series, our simulations allowed us to compare the relative evidence for alternate mechanisms that might have caused the observed shift.

276 The dynamics that we describe during the first part of the series are consistent with previous 277 work, which indicated that precipitation positively affects caterpillar population growth rates and 278 interacts with endogenous dynamics of overcompensating negative direct density-dependence (Karban & de Valpine 2010; Karban et al. 2017). Mechanisms proposed to explain the effect of precipitation 279 include limited resources during summer drought (Karban & de Valpine 2010), or negative effects of 280 281 precipitation on predatory ants (Karban et al. 2017). Parasitism and viral infection are potential 282 mechanisms for both direct and delayed density-dependence in this population, as they are in many 283 insects and particularly Lepidoptera (Myers & Cory 2013, 2016). Parasitism and viral infection can 284 induce density-dependence in insect population dynamics when parasitoids are host-specific and 285 display numerical responses to host density, and when virus transmission depends on host density 286 (Myers & Cory 2013). Delays in the action of density-dependence may be caused by delayed numerical 287 responses of parasitoids (Myers & Cory 2013), or a greater prevalence of covert viral infections or viral 288 occlusion bodies in the environment after high-density years (Myers & Cory 2016). Long-term 289 monitoring data revealed no delayed density-dependent parasitism in this population (Karban & de 290 Valpine 2010). However, laboratory rearing of *A. virginalis* from multiple monitored populations 291 suggested a delayed-density dependent rate of viral infection (Pepi, Pan & Karban, unpublished data) as is the case in many Lepidoptera (Anderson & May 1980; Myers & Cory 2013, 2016). 292 293 In contrast, the dynamics of the second part of the series (2004-2019) were not predictable from 294 our previous understanding of caterpillar population dynamics derived from analyses of time series that

were long by ecological standards (20 years, 1986-2006; Karban & de Valpine 2010). This type of

296 non-stationarity due to shifts in climatic regimes has large implications for forecasting and managing 297 populations of threatened or pest species, because such shifts have the potential to obfuscate 298 predictions about management actions. Ecological forecasting has become an urgent goal in light of 299 global change and unprecedented human pressures on the biosphere (Clark et al. 2001). Whereas most 300 literature has focused on predicting ecological state variables (e.g., population size; Dietze 2017), we 301 examined how changing patterns of climate interacted with endogenous population drivers to 302 qualitatively change dynamics. This illustrates the importance of considering the interaction between 303 endogenous population drivers and exogenous climate variation in projecting population dynamics into 304 the future, and argues that incorporating changes in patterns of climate into predictions is essential. 305 The fact that the qualitative range of dynamics in populations is to some extent limited (i.e., 306 there are not ten million types of population dynamics; Lawton 1992) makes predicting shifts in 307 population dynamics due to climate change a more attainable prospect. Consistent with this, most 308 populations have either first or second order, and either chaotic or non-chaotic dynamics (Types I-IV and I'-IV' in Fig. 2; also see Royama 1992), in addition to some other important axes of variation 309 310 (Turchin 2003; Barraquand et al. 2017). Ecologically, the presence of overcompensating (type II-III) 311 density dependence, a stable equilibrium (type I), or longer period cycles (type IV) have important 312 effects on species interactions, ecosystem dynamics, and how climate is likely to affect dynamics 313 (Ranta et al. 2000; Ims et al. 2008). Mechanistic studies separating endogenous from exogenous 314 components of dynamics can distinguish whether observed dynamics, such as cycles, arise from 315 different mechanisms. Some of these mechanisms include self-sustaining or noise-sustained second 316 order dynamics, externally-forced first order dynamics (Barraquand et al. 2017), and non-cyclic 317 dynamics that mask endogenous second-order dynamics, as we found support for in the present study 318 (Greenman & Benton 2003). The application of methods such as those implemented in the present 319 study can help distinguish between different possible combinations of endogenous and exogenous 320 components of a system that might have generated the observed dynamics. Doing so will improve our

321 ability to understand how changes in exogenous forcing due to climate change are likely to affect future

322 population dynamics.

#### 323 Acknowledgments

Many former students of RK contributed to census data collection, and this work would not have been possible without them. These censuses were conducted at the UC Bodega Marine Reserve and we thank Peter Connors and Jackie Sones for facilitating our work there. We would also like to thank Eric Post, Jay Rosenheim, Rolf Ims, and Louis Botsford for help improving the manuscript. This

- 328 work has been supported by NSF, most recently NSF-LTREB-1456225
- 329 Data Accessibility

330 Data will be archived on HAL upon acceptance.

#### 331 References

- Alonso, D., McKane, A.J. & Pascual, M. (2007). Stochastic amplification in epidemics. *J. R. Soc. Interface*, 4, 575–582.
- Anderson, R.M. & May, R.M. (1980). Infectious Diseases and Population Cycles of Forest Insects.
   *Science (80-. ).*, 210, 658–661.
- Andrewartha, H.G. & Birch, L.C. (1954). *The distribution and abundance of animals*. University of
   Chicago Press.
- Antonio, F.D.N. & Stigler, J.L.A.M. (2009). tsDyn: Time series analysis based on dynamical systems
  theory.
- Arnaud, P.H. (1978). *Host Parasite Catalog of North American Tachinidae (Diptera)*. Department of
   Agriculture, Science and Education Administration.
- 342 Barraquand, F., Louca, S., Abbott, K.C., Cobbold, C.A., Cordoleani, F., DeAngelis, D.L., et al. (2017).
- 343 Moving forward in circles: challenges and opportunities in modelling population cycles. *Ecol.*
- 344 *Lett.*, 20, 1074–1092.
- 345 Bjørnstad, O.N. & Grenfell, B.T. (2001). Noisy clockwork: time series analysis of population

- fluctuations in animals. *Science*, 293, 638–43.
- Cazelles, B., Chavez, M., McMichael, A.J. & Hales, S. (2005). Nonstationary influence of El Niño on
  the synchronous dengue epidemics in Thailand. *PLoS Med.*, 2, 0313–0318.
- Clark, J.S., Carpenter, S.R., Barber, M., Collins, S., Dobson, A., Foley, J.A., *et al.* (2001). Ecological
  forecasts: an emerging imperative. *Science (80-. ).*, 293, 657–660.
- 351 Cloern, J.E., Hieb, K.A., Jacobson, T., Sans, B., Di Lorenzo, E., Stacey, M.T., et al. (2010). Biological
- communities in San Francisco Bay track large-scale climate forcing over the North Pacific.
   *Geophys. Res. Lett.*, 37, 1–6.
- 354 Cornulier, T., Yoccoz, N.G., Bretagnolle, V., Brommer, J.E., Butet, A., Ecke, F., et al. (2013). Europe-
- 355 wide dampening of population cycles in keystone herbivores. *Science (80-. ).*, 340, 63–66.
- 356 Coumou, D. & Rahmstorf, S. (2012). A decade of weather extremes. *Nat. Clim. Chang.*, 2, 491–496.
- 357 Dietze, M.C. (2017). Prediction in ecology: a first-principles framework. *Ecol. Appl.*, 27, 2048–2060.
- English-Loeb, G.M., Brody, A.K. & Karban, R. (1993). Host-plant-mediated interactions between a
  generalist folivore and its tachinid parasitoid. *J. Anim. Ecol.*, 62, 465.
- Gelman, A. & Rubin, D.B. (1992). Inference from iterative simulation using multiple sequences. *Stat. Sci.*, 7, 457–472.
- Gouhier, T.C., Grinsted, A. & Simko, V. (2019). R package biwavelet: Conduct Univariate and
  Bivariate Wavelet Analyses.
- Greenman, J. V. & Benton, T.G. (2003). The amplification of environmental noise in population
   models: Causes and consequences. *Am. Nat.*, 161, 225–239.
- Ims, R.A., Henden, J.A. & Killengreen, S.T. (2008). Collapsing population cycles. *Trends Ecol. Evol.*,
  23, 79–86.
- Karban, R., Grof-Tisza, P. & Holyoak, M. (2017). Wet years have more caterpillars: Interacting roles of
   plant litter and predation by ants. *Ecology*.
- 370 Karban, R., Karban, C., Huntzinger, M., Pearse, I. & Crutsinger, G. (2010). Diet mixing enhances the

- 371 performance of a generalist caterpillar, Platyprepia virginalis. *Ecol. Entomol.*, 35, 92–99.
- 372 Karban, R., Mata, T.M., Grof-Tisza, P., Crutsinger, G. & Holyoak, M.A. (2013). Non-trophic effects of
- 373 litter reduce ant predation and determine caterpillar survival and distribution. *Oikos*, 122, 1362–
  374 1370.
- Karban, R. & de Valpine, P. (2010). Population dynamics of an Arctiid caterpillar-tachinid parasitoid
  system using state-space models. *J. Anim. Ecol.*, 79, 650–661.
- 377 Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan.
- Lawton, J.H. (1992). There are not 10 million kinds of population dynamics. *Oikos*, 63, 337–338.
- 379 Martyn, A., Best, N., Cowles, K., Vines, K., Bates, D., Almond, R., et al. (2019). Package ' coda ':
- 380 Output Analysis and Diagnostics for MCMC.
- Myers, J.H. & Cory, J.S. (2013). Population Cycles in Forest Lepidoptera Revisited. *Annu. Rev. Ecol. Evol. Syst.*, 44, 565–592.
- Myers, J.H. & Cory, J.S. (2016). Ecology and evolution of pathogens in natural populations of
  Lepidoptera. *Evol. Appl.*, 9, 231–247.
- Nicholson, A.J. (1933). The balance of animal populations. J. Anim. Ecol., 2, 132 178.
- Parmesan, C. (2006). Ecological and evolutionary responses to recent climate change. *Annu. Rev. Ecol. Evol. Syst.*, 37, 637–669.
- 388 Plummer, M. (2019). rjags: Bayesian Graphical Models using MCMC.
- Ranta, E., Lundberg, P., Kaitala, V. & Laakso, J. (2000). Visibility of the environmental noise
  modulating population dynamics. *Proc. R. Soc. B Biol. Sci.*, 267, 1851–1856.
- Rodó, X., Pascual, M., Fuchs, G. & Faruque, A.S.G. (2002). ENSO and cholera: A nonstationary link
  related to climate change? *Proc. Natl. Acad. Sci. U. S. A.*, 99, 12901–12906.
- 393 Rouyer, T., Fromentin, J.-M., Stenseth, N.C. & Cazelles, B. (2008). Analysing multiple time series and
- extending significance testing in wavelet analysis. *Mar. Ecol. Prog. Ser.*, 359, 11–23.
- 395 Royama, T. (1992). *Analytical Population Dynamics*. Chapman & Hall, London.

- Simon Wang, S.Y., Yoon, J.H., Becker, E. & Gillies, R. (2017). California from drought to deluge. *Nat. Clim. Chang.*, 7, 465–468.
- 398 Stigler, M. (2019). seglm: Segmented/threshold regression methods.
- Swain, D.L., Langenbrunner, B., Neelin, J.D. & Hall, A. (2018). Increasing precipitation volatility in
  twenty-first-century California. *Nat. Clim. Chang.*, 8, 427–433.
- 401 Thomson, J.R., Kimmerer, W.J., Brown, L.R., Newman, K.B., Mac Nally, R., Bennett, W.A., et al.
- 402 (2010). Bayesian change point analysis of abundance trends for pelagic fishes in the upper San
  403 Francisco Estuary. *Ecol. Appl.*, 20, 1431–1448.
- 404 Tomé, T. & De Oliveira, M.J. (2009). Role of noise in population dynamics cycles. *Phys. Rev. E Stat.*405 *Nonlinear, Soft Matter Phys.*, 79, 1–8.
- 406 Turchin, P. (2003). *Complex Population Dynamics: A Theoretical/Empirical Synthesis*. Princeton
  407 University Press, Princeton.
- Vehtari, A., Gelman, A. & Gabry, J. (2017). Practical Bayesian model evaluation using leave-one-out
  cross-validation and WAIC. *Stat. Comput.*, 27, 1413–1432.
- Walther, G., Post, E., Convey, P., Menzel, A., Parmesan, C., Beebee, T.J.C., *et al.* (2002). Ecological
  responses to recent climate change. *Nature*, 416, 389–395.
- 412 Yu-Sung Su & Yajima, M. (2015). R2jags: Using R to Run "JAGS."
- 413
- 414
- 415
- 416
- 417
- 418 **Tables and Figures**



Figure 1: (a) Time series of caterpillar population counts per 100 m<sup>2</sup> (solid black line) and total annual 420 421 precipitation (dashed blue line); (c) local wavelet transform of caterpillar population counts; (e) local 422 wavelet transform of total annual precipitation; (g) wavelet coherence between total annual precipitation and caterpillar population counts; (b,d,f) global spectra of (a,c,e); (h) global coherence of 423 424 (g), total annual precipitation and caterpillar population counts. The dashed red line through (a,c,e,g) 425 represents the time threshold found in the change-point analysis including precipitation. Caterpillar density and spectral period are shown on a log scale; total annual precipitation is shown on the right 426 427 axis. Solid black lines in (c,e,g) delimit regions of significant periodicity or coherence at a 95% 428 confidence level from a bootstrap test. Color bars in (c,e,g) show the scale power from low (blue) to 429 high (red). Caterpillar wavelet spectrum is shown in (a) with a solid line, and precipitation wavelet spectrum is shown with a dashed line. Dashed red lines in (d,f) show the 95% confidence threshold 430 431 from a bootstrap test; peaks to the right of the line represent significant periodicity.

Climate variation and population dynamics



Figure 2: Bayesian posterior 90% and 95% (broad to narrow lines) posterior intervals, and point
estimates of parameters from Poisson state-space models. Estimates from the whole series are shown
in black (1986-2019), before the threshold in blue (1986-2004), and after the threshold in red (20042019).



Figure 3. Posterior distributions of Bayesian state space models fit to the first part of the series (1986-2004), the second part of the series (2004-2019) and the whole series (1986-2019), plotted in the
Royama parameter plane, showing a shift from type III to type IV dynamics. Open circles represent the
median of the posterior distributions.



Figure 4. Simulation 90% and 95% (broad to narrow lines) posterior intervals and point estimates of
dissimilarity values relative to the true population trajectories, from multiple mechanistic scenarios.

- <del>т</del>Ј-

Model	Period	<i>a</i> <sub>1 [P]</sub>	<i>a</i> <sub>2</sub> [P]	$\boldsymbol{\beta_1}_{[P]}$
Without Precipitation	1986-2002	-0.56 [P=0.098]	-0.44 [P=0.211]	
-	2002-2019	0.35 [P=0.109]	-0.52 [P=0.019]	
With Precipitation	1986-2004	-0.57 [P=0.091]	-0.41 [P=0.209]	-0.01 [P=0.098]
I	2004-2019	0.510 [P=0.027]	-0.286 [P=0.218]	1.27 [P=0.026]
Table 1. Result	s of change-point	analysis, including para	meter estimates and P v	alues, from models
with and withou	ut precipitation, b	efore and after change-p	oint thresholds.	

# 477 Supplementary Materials:

Process model	$\Delta$ WAIC	WAIC	a <sub>0 [2.5%,97.5%]</sub>	$a_{1}$ [2.5%,97.5%]	$a_{2}$ [2.5%,97.5%]	$\beta_{1[2.5\%,97.5\%]}$	
1986-2019:							
$X_t \sim a_0 + a_1 X_{t-1} + a_2 X_{t-2} + \beta_1 Precip_{t-1}$	1.38	201.78	-1.28 [-2.13, -0.46]	0.11 [-0.31, 0.53]	-0.30 [-0.70, 0.01]	0.30 [-0.18, 0.78]	
$X_t \sim a_0 + a_1 X_{t-1} + \beta_1 Precip_{t-1}$	1.00	201.40	-1.01 [-1.50, -0.52]	0.03 [-0.29, 0.35]	-	0.36 [0.01, 0.70]	
$X_t \sim a_0 + a_1 X_{t-1} + a_2 X_{t-2}$	1.36	201.76	-1.34 [-1.62, -0.52]	0.11 [-0.32, 0.53]	-0.35 [-0.750, 0.05]	-	
$X_t \sim a_0 + a_1 X_{t-1}$	0.96	200.76	-1.05 [-1.75, -0.36]	0.05 [-0.37, 0.46]	-	-	
$X_t \sim a_0 + \beta_1 Precip_{t-1}$	0.0*	200.4*	0.05 [-0.28, 0.38]	-	-	0.40 [0.018, 1.04	
$X_t \sim a_0$	0.13	200.53	0.04 [-0.59, 0.68]	-	-	-	
1986-2004:							
$X_{t} \sim a_{0} + a_{1}X_{t-1} + a_{2}X_{t-2} + \beta_{1}Precip_{t-1}$	0.52	117.37	-1.74 [-2.92, -0.61]	-0.63 [-1.29, 0.03]	-0.27 [-0.89, 0.34]	0.26 [-0.27, 0.78	
$X_{t} \sim a_{0} + a_{1}X_{t-1} + \beta_{1}Precip_{t-1}$	0.57	117.41	-1.48 [-2.17, -0.81]	-0.57 [-1.10, -0.03]	-	0.27 [-0.24, 0.77	
$X_{t} \sim a_{0} + a_{1}X_{t-1} + a_{2}X_{t-2}$	0.00*	116.85*	-1.68 [-2.87, -0.55]	-0.57 [-1.23, 0.08]	-0.26 [-0.90, 0.38]	-	
$X_t \sim a_0 + a_1 X_{t-1}$	0.11	116.96	-1.46 [-2.17, -0.78]	-0.53 [-1.06, -0.03]	-	-	
$X_t \sim a_0 + \beta_1 Precip_{t-1}$	0.72	117.57	-0.17 [-1.06, 0.72]	-	-	0.09 [-0.81, 0.98	
$X_t \sim a_0$	0.81	117.66	-0.18 [-1.03, 0.68]	-	-	-	
2004-2019:							
$X_t \sim a_0 + a_1 X_{t-1} + a_2 X_{t-2} + \beta_1 Precip_{t-1}$	0.00*	86.32*	-0.58 [-1.98, 0.79]	0.46 [-0.05, 0.96]	-0.19 [-0.74, 0.36]	0.92 [0.01, 1.87]	
$X_t \sim a_0 + a_1 X_{t-1} + \beta_1 Precip_{t-1}$	1.65	87.97	-0.22 [-1.50, 0.96]	0.60 [0.01, 1.15]	-	1.14 [0.24, 1.15]	
$X_t \sim a_0 + a_1 X_{t-1} + a_2 X_{t-2}$	0.53	86.85	-1.30 [-2.78, 0.06]	0.340 [-0.23, 0.89]	-0.46 [-1.02, 0.01]	-	
$X_t \sim a_0 + a_1 X_{t-1}$	1.13	87.45	-0.72 [-2.27, 0.71]	0.35 [-0.32, 1.00]	-	-	
$X_t \sim a_0 + \beta_1 Precip_{t-1}$	1.76	88.08	0.45 [-0.35, 1.23]	-	-	1.37 [0.45, 2.28]	
$X_t \sim a_0$	1.02	87.34	0.33 [-0.79, 1.46]	-	-	-	

479 the process model structure. Change in WAIC relative to the best model (ΔWAIC), WAIC, and parameter

480 estimates with 95% posterior intervals are shown. WAIC values within  $\Delta$ WAIC <2 of the best model are

481 bolded, and the best model is bolded. Parameter estimates the 95% posterior intervals which do not

482 overlap zero are bolded as well.

	Series	Original	Whole series, fitted β <sub>1</sub>	Part I, fitted β <sub>1</sub>	Part II, fitted β <sub>1</sub>	Whole series, equal β <sub>1</sub>	Part I, equal β <sub>1</sub>	Part II, equal β <sub>1</sub>	Part II, no a <sub>1</sub> , a <sub>2</sub>	
	Original	0								
	Whole series, fitted $\beta_1$	22.14	0							
	Part I, fitted $\beta_1$	22.80	10.38	0						
	Part II, fitted $\beta_1$	17.55	10.17	16.51	0					
	Whole series, equal $m eta_1$	18.54	11.87	15.89	11.30	0				
	Part I, equal $\beta_1$	21.42	19.56	18.19	16.44	17.58	0			
	Part II, equal $\beta_1$	17.55	10.17	16.51	0	6.22	16.5	0		
	Part II, no $a_1, a_2$	19.72	12.73	15.84	6.52	6.37	13.75	6.67	0	
496	Table S2.   Dissimilar	rity matrix	x of simu	lated time	e series fro	om fitted	state-spa	ce proces	s models, v	with
497	original fitted parame	eters and v	with effec	ct of preci	pitation s	et to equa	al at the h	nighest fit	ted value	
498	( $\beta_1$ =0.922), all compa	ared with	the origin	nal observ	ved time s	eries. Lo	west diss	imilaritie	s relative to	o the
499	original series for sim	nulations	with fitte	d or equa	l $\beta_1$ value	s are bold	ded.			
500										
501										
502										
503										
504										
505										
506										
507										
508										
509										

Series	Parameter	$a_0$	$a_1$	$a_2$	$\beta_1$
Whole Series	<i>a</i> <sub>0</sub>	1			
	<i>a</i> <sub>1</sub>	0.584	1		
	a <sub>2</sub>	0.551	-0.014	1	
	$\beta_1$	0.109	0.001	0.157	1
Part I	<i>a</i> <sub>0</sub>	1			
	a <sub>1</sub>	0.744	1		
	<i>a</i> <sub>2</sub>	0.739	0.465	1	
	$\beta_1$	-0.116	-0.214	-0.049	1
Part II	<i>a</i> <sub>0</sub>	1			
	<i>a</i> <sub>1</sub>	0.491	1		
	a <sub>2</sub>	0.628	-0.116	1	
	$\beta_1$	0.501	0.207	0.520	1

**Table S3**. Cross-correlation matrices between parameter estimates from MCMC chains the full state

513 space model from the whole series, part I and part II.

Year	Caterpillar count	Lupine area (m <sup>2</sup> )
1986	490	400
1987	8	101.35
1988	12	53.75
1989	25	51
1990	48	61.24
1991	7	41.5
1992	71	63.75
1993	5	29.25
1994	16	59.75
1995	15	20.5
1996	40	18.05
1997	2	20
1998	8	20
1999	12	18
2000	8	38
2001	40	31.5
2002	18	63
2003	52	45.5
2004	3	64.5
2005	0	57.5
2006	2	34
2007	51	35
2008	40	32.5
2009	9	62
2010	2	51.5
2011	23	27.75
2012	27	15.5
2013	2	40
2014	8	33
2015	3	29.5
2016	13	38
2017	7	30
2018	22	21
2019	131	26

 Table S4.
 Year, caterpillar counts, and area of lupine surveyed.



**Figure S1.** MCMC trace and density plot of parameters from full state space model of the whole

533 series.



537 Figure S2. MCMC trace and density plots of parameters from full state space model of the first part of538 the series.









Figure S4. Posterior predictive simulations from full state space model of the whole series, with the
observed trajectory in black, and one-step ahead simulations from 15 draws from the posterior in blue.





550 Figure S5. Posterior predictive simulations from full state space model of the first part of the series,

551 with the observed trajectory in black, and one-step ahead simulations from 15 draws from the posterior

552 in blue.



554

Figure S6. Posterior predictive simulations from full state space model of the second part of the series,
with the observed trajectory in black, and one-step ahead simulations from 15 draws from the posterior
in blue.



**Figure S7**. Wavelet transformations of simulated trajectories from fitted state-space process models. (a,c,e) Simulations using original fitted values, and (b,d,f) using fitted values for density-dependence but the highest values for precipation. (a,b) Models of the whole series, (c,d) before the threshold, and (e,f) after the threshold. Black lines delimit regions of significant periodicity or coherence at a 95% confidence level from a bootstrap test. Color bars show the scale for power from low (blue) to high (red).



Figure S8. Fifty simulation trajectory results (blue) vs. true population trajectory (black) from
simulation based on the models (left to right, top to bottom) from the whole series, part I, part II, the
whole series with precipitation values from part II, part I with precipitation values from part II, and part
II without density dependence.